

WHAT IS CLAIMED IS:

5010A > 1. A device controller, comprising:

an operation section which can send an operation signal to a device; and

a controlling section for notifying, at a point in time at which the device becomes able to receive the operation signal from the operation section, that the device has become able to receive the operation signal from the operation section, by actuating a function that the device has for achieving an original object to thereby change a physical state of the device to a state that is different from the present state of the device.

2. A device controller, comprising:

an operation section which can send an operation signal to a device disposed at a position apart from the operation section; and

a controlling section for changing a physical state of the device to a state that is different from the present state of the device and for returning, after the changing, the physical state of the device to an initial state of the device, by actuating a function that the device has for achieving an original object, at a point in time at which the controlling section becomes able to receive the operation signal from the operation section.

5010A' > 3. The device controller according to claim 2, wherein

the device includes a driving section for displacing a driven part on the basis of the operation signal from the operation section, and

at the point in time at which the controlling section becomes able to receive the operation signal from the operation section, the controlling section drives the driving section to displace the driven part in a predetermined direction by a predetermined amount, and, immediately after the driven part is displaced in the predetermined amount, drives the driving section to displace the driven part in a direction opposite to the predetermined direction by the predetermined amount.

4. The device controller according to claim 2, wherein

the operation section includes an operation section main body that is displaceable within a predetermined range in a vehicle compartment and detecting sections, with each detecting section being connected to the controlling section and detecting the operation section main body at different positions within the predetermined range,

the device is mounted in the vehicle, and

the operation section can send the operation signal to the device when the operation section main body is in a position corresponding to the device within the predetermined range.

5. The device controller according to claim 3, wherein

the operation section includes an operation section main body that is displaceable within a predetermined range in a vehicle compartment and detecting sections, with each detecting section being connected to the controlling section and detecting the operation section main body at different positions within the predetermined range,

the device is mounted in the vehicle, and

the operation section can send the operation signal to the device when the operation section main body is in a position corresponding to the device within the predetermined range.

6. The device controller according to claim 2, wherein

the operation section includes an operation section main body that is displaceable within a predetermined range in a vehicle compartment and detecting sections, with each detecting section being connected to the controlling section and detecting the operation section main body at different positions thereof within the predetermined range,

the device is mounted in the vehicle, and

when one detecting section detects the operation section main body, the operation section can send the operation signal to the device that corresponds to the detecting section, and

a direction indicated by the operation section main body substantially corresponds to a position of the device corresponding to the detecting section.